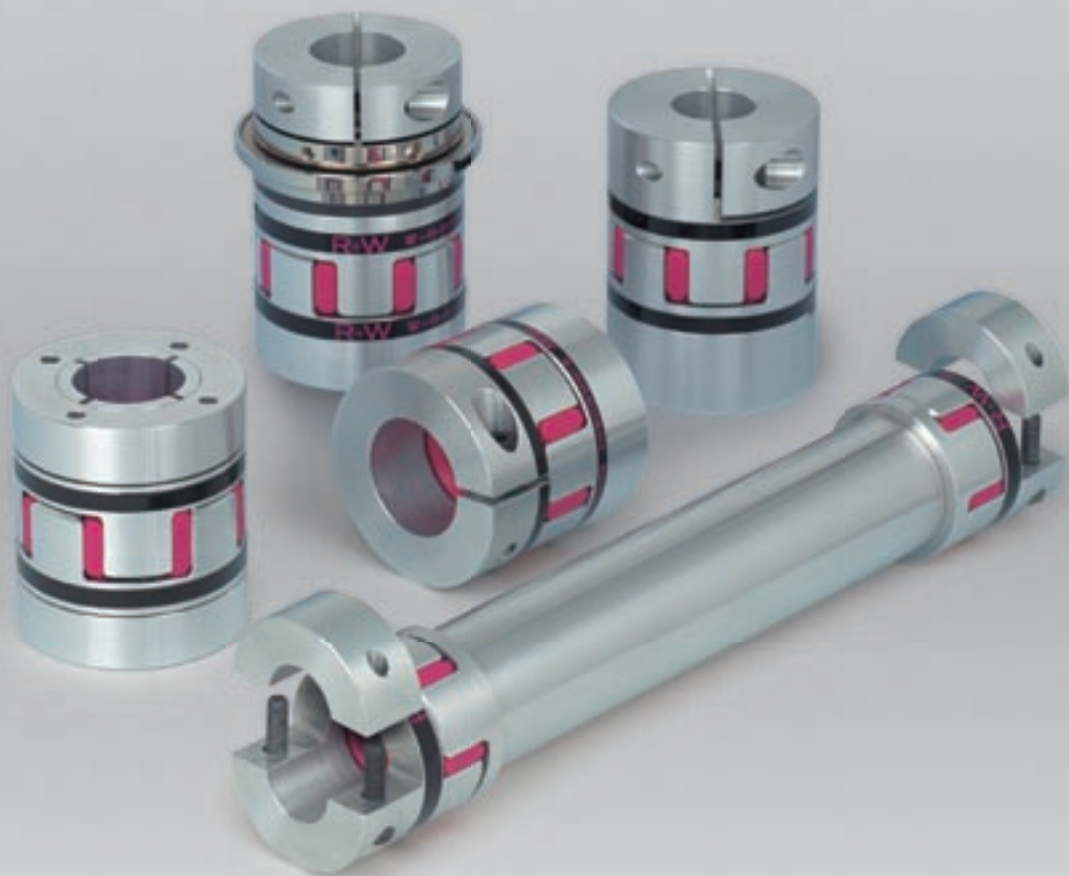


**PRECISE AND COMPACT.**

**SERVOMAX®**

**ELASTOMER COUPLINGS**

**SERIES EK | 2 – 2000 Nm**



**R+W®**  
COUPLING TECHNOLOGY

THE ULTIMATE COUPLING FROM 2 – 2000 Nm

[www.rwcouplings.com](http://www.rwcouplings.com)

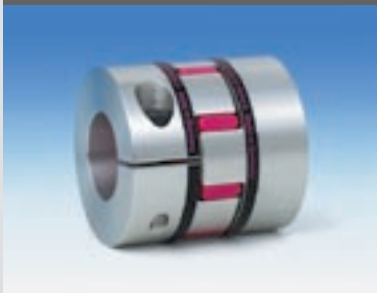
optional  
stainless steel

## MODELS

## PROPERTIES

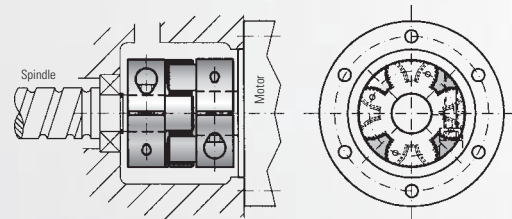
## APPLICATION EXAMPLES

### EKL



#### with clamping hub, compact version

- short compact design
- low inertia
- easy assembly



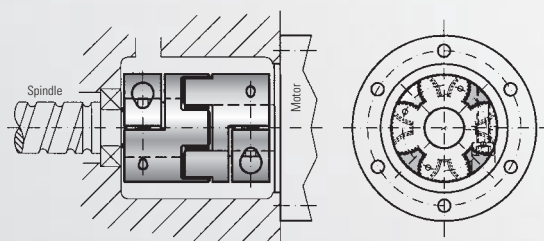
see page 5

### EK2



#### with clamping hub

- very smooth running
- counterbalanced type
- easy assembly



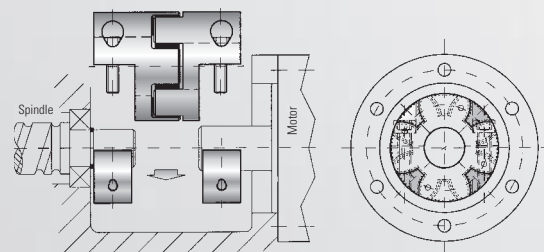
see page 6

### EKH



#### with split clamping hubs

- easy assembly
- radial mounting, due to split clamping hubs



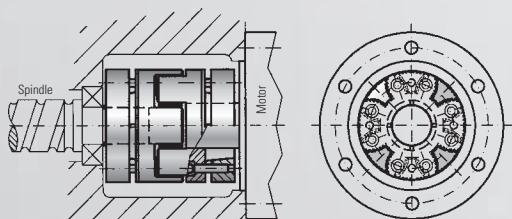
see page 7

### EK6



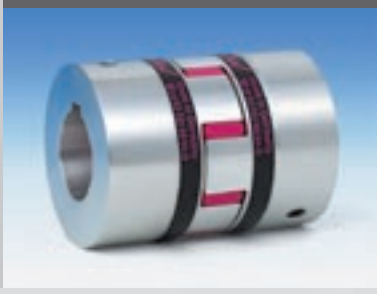
#### with conical clamping ring

- very smooth running
- high clamping forces
- axially mountable



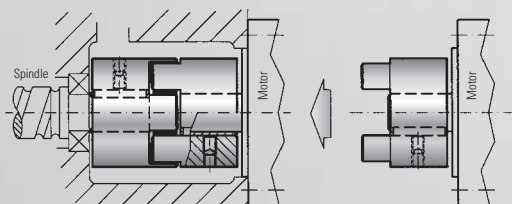
see page 8

### EK1



#### with keyway-connection

- favorably priced design
- easy to modify



see page 9

## MODELS

## PROPERTIES

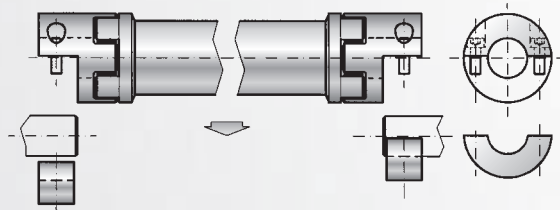
## APPLICATION EXAMPLES

### EZ2



#### line shaft with split clamping hub

- radial mounting due to split hubs
- no intermediate support bearing necessary
- conical clamping hubs available
- length up to 4 m



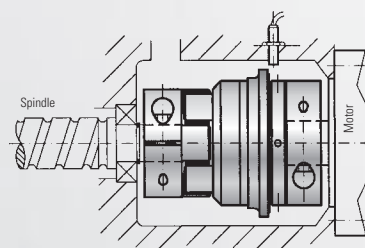
see page 10/11

### ES2



#### torque limiter with clamping hub

- reliable torque overload protection
- backlash free due to patented R+W design
- easy to mount



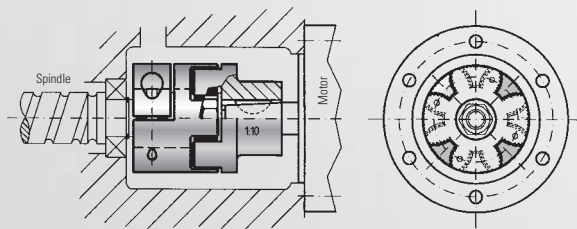
see page 12/13/14

### EK4



#### for conical shaft ends

- for conical shaft ends e.g. Fanuc motors
- easy mounting
- conical hub mounts axially



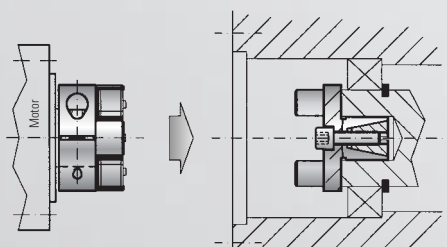
see page 15

### EK7



#### with expanding shaft

- axial hub mounting with expanding shaft
- very smooth running
- high clamping forces



see page 16/17

### EEx



#### for the use in explosive environments

- available for the full product range
- for the hazardous areas 1/21 and 2/22 the SERVOMAX EEx Elastomer couplings are registered according to the directive ATEX 95/137



see page 19



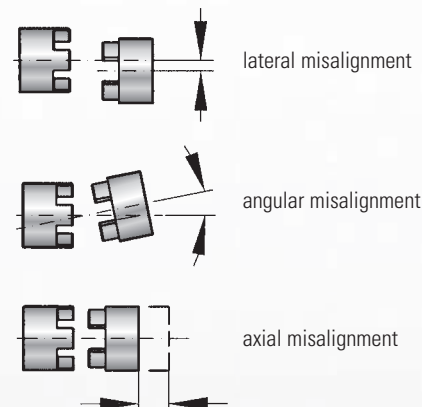
# SERVOMAX® ELASTOMER COUPLINGS

## Areas of application:

- Servo drives
- Machine tools
- Packaging machinery
- Plant automation
- Printing machinery
- Industrial robots
- Measurement and positioning units
- general mechanical engineering
- Linking screw jacks, linear actuators, encoders

## Properties of the product range:

- vibration dampening
- electrically insulating (standard)
- backlash-free
- press-fit design
- compensation of lateral-, angular- and axial misalignment



## Function

The equalizing element of an EK coupling is the elastomer insert. It transmits the torque without backlash and vibration. The elastomer insert defines the features of the entire coupling and/or of the entire drive system.

The coupling is backlash free due to pretensioning of the elastomer insert between the two coupling halves. The Servomax-Coupling compensates for lateral, angular and axial misalignment.



**Type A**  
Shore hardness 98 Sh A



**Type B**  
Shore hardness 64 Sh D



**Type C**  
Shore hardness 80 Sh A






**Type D\***  
Shore hardness 92 Sh A

## Specification of the Elastomer inserts

Type	Shore hardness	Color	Material	Relative damping ( $\psi$ )	Temperature range	Features
A	98 Sh A	red	TPU	0,4 - 0,5	-30°C to +100°C	high damping
B	64 Sh D	green	TPU	0,3 - 0,45	-30°C to +120°C	high torsional stiffness
C	80 Sh A	yellow	TPU	0,3 - 0,4	-30°C to +100°C	very high damping
D*	92 Sh A	black	TPU	0,3 - 0,45	-10°C to +90°C	electrically conductive*

\* Due to the electrically conductive properties of the insert electrostatic load of the coupling is prevented. This eliminates sparks during normal operation (Explosive areas). Technical datas available.

The values of the relative damping were determined at 10 Hz and +20°C.

Model row EK		Series																										
		2			5			10			20			60			150			300			450			800		
Type (Elastomer insert)		A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C
Static torsional stiffness (Nm/rad)	C <sub>T</sub>	50	115	17	150	350	53	260	600	90	1140	2500	520	3290	9750	1400	4970	10600	1130	12400	18000	1280	15100	27000	4120	41300	66080	10320
Dynamic torsional stiffness (Nm/rad)	C <sub>Tdyn</sub>	100	230	35	300	700	106	541	1650	224	2540	4440	876	7940	11900	1350	13400	29300	3590	23700	40400	6090	55400	81200	11600	82600	180150	28600
Lateral  (mm)	Max. values	0,08	0,06	0,1	0,08	0,06	0,1	0,1	0,08	0,12	0,1	0,08	0,15	0,12	0,1	0,15	0,15	0,12	0,2	0,18	0,14	0,25	0,2	0,18	0,25	0,25	0,2	0,3
Angular  (mm)		1	0,8	1,2	1	0,8	1,2	1	0,8	1,2	1	0,8	1,2	1	0,8	1,2	1	0,8	1,2	1	0,8	1,2	1	0,8	1,2	1	0,8	1,2
Axial  (mm)		±1			±1			±1			±2			±2			±2			±2			±2			±2		

Static torsional stiffness at 50%  $T_{KN}$

Dynamic torsional stiffness at  $T_{KN}$

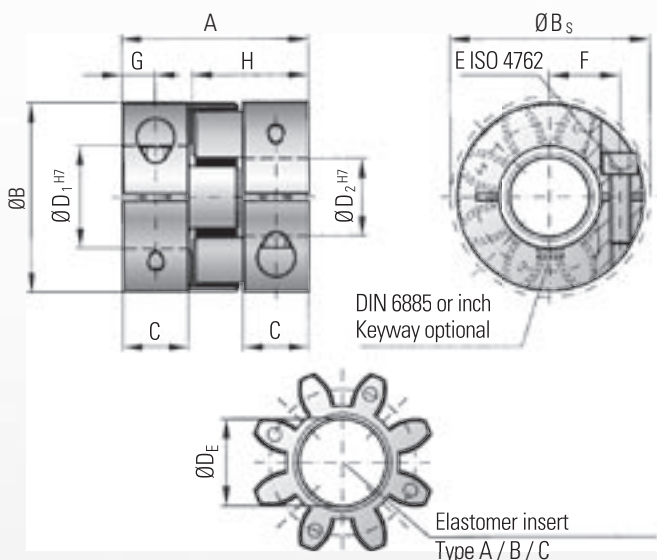
1 Nm = 8,85 in lbs



optional  
stainless steel

# MODEL EKL

## TECHNICAL SPECIFICATIONS



### Properties:

- short compact design
- easy assembly
- vibration dampening
- electrically insulating
- backlash-free
- press-fit design

### Material:

Clamping hub: up to series 450 high strength aluminum, from series 800 and up steel  
Elastomer insert: precision molded, wear resistant, and thermally stable polymer

### Design:

Two coupling hubs are concentrically machined with concave driving jaws

### \*Speeds:

Over 4.000 rpm a finely balanced version is available

### Tolerance:

On the hub/shaft connection 0,01 to 0,05 mm

Model EKL			Series																											
			2			5			10			20			60			150			300			450			800			
Type (Elastomer insert)			A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	
Rated torque (Nm)	T <sub>KN</sub>	2	2,4	0,5	9	12	2	12,5	16	4	17	21	6	60	75	20	160	200	42	325	405	84	530	660	95	950	1100	240		
Max. torque** (Nm)	T <sub>Kmax</sub>	4	4,8	1	18	24	4	25	32	6	34	42	12	120	150	35	320	400	85	650	810	170	1060	1350	190	1900	2150	400		
Overall length (mm)	A	20			26			32			50			58			62			86			94			123				
Outer diameter (mm)	B	16			25			32			42			56			66,5			82			102			136,5				
Outer diameter with screwhead (mm)	B <sub>S</sub>	17			25			32			44,5			57			68			85			105			139				
Mounting length (mm)	C	6			8			10,3			17			20			21			31			34			46				
Inner diameter range H7 (mm)	D <sub>1/2</sub>	3 - 8			4 - 12,7			4 - 16			8 - 25			12 - 32			19 - 35			20 - 45			28 - 60			35 - 80				
Inner diameter max. (elastomer) (mm)	D <sub>E</sub>	6,2			10,2			14,2			19,2			27,2			30,2			38,2			46,2			60,5				
Mounting Screw (ISO 4762/12.9)	E	M2			M3			M4			M5			M6			M8			M10			M12			M16				
Tightening torque of the mounting screw (Nm)		0,6			2			4			8			15			35			70			120			290				
Distance between centers (mm)	F	5,5			8			10,5			15,5			21			24			29			38			50,5				
Distance (mm)	G	3			4			5			8,5			10			11			15			17,5			23				
Hub length (mm)	H	12			16,7			20,7			31			36			39			52			57			74				
Moment of inertia (10 <sup>-3</sup> kgm²)	J <sub>1</sub> /J <sub>2</sub>	0,0003			0,001			0,01			0,01			0,08			0,15			0,4			1,3			7,8				
Approx. weight (kg)		0,008			0,02			0,05			0,12			0,3			0,5			0,9			1,5			8,5				
Speed* (rpm)		28.000			22.000			20.000			19.000			14.000			11.500			9.500			8.000			4.000				

Information about static and dynamic torsional stiffness as well as max. possible misalignment see page 4

1 Nm = 8,85 in lbs

\*\* Maximum transferable torque of the clamping hub depends on the bore diameters (bore/shaft clearance 0,01 mm to 0,05 mm shaft oiled)

Series	Ø 3	Ø 4	Ø 5	Ø 8	Ø 16	Ø 19	Ø 25	Ø 30	Ø 32	Ø 35	Ø 45	Ø 50	Ø 55	Ø 60	Ø 65	Ø 70	Ø 75	Ø 80
2	0,2	0,8	1,5	2,5														
5		1,5	2	8														
10			4	12	32													
20				20	35	45	60											
60					50	80	100	110	120									
150						120	160	180	200	220								
300						200	230	300	350	380	420							
450								420	480	510	600	660	750	850				
800										700	750	800	835	865	900	925	950	1.000

Higher torque through additional key possible.

### Ordering example

EKL / 60 / A / 19 / 24 / XX

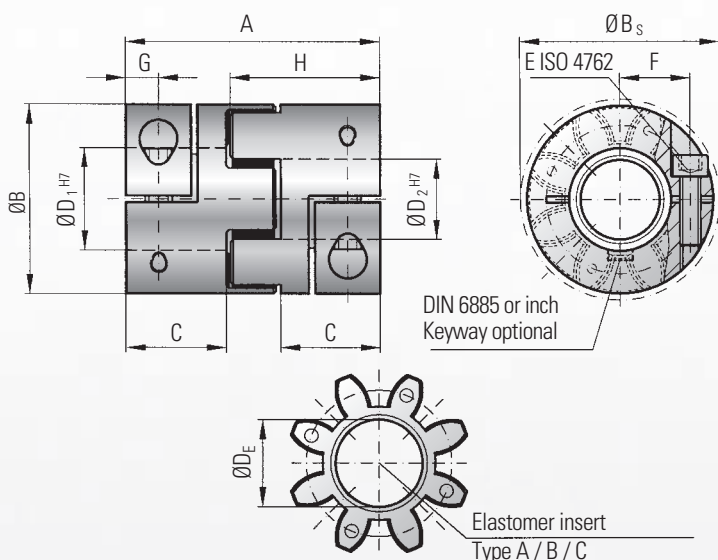
Model  
Series  
Type Elastomer insert  
Bore Ø D1 H7  
Bore Ø D2 H7  
Non standard e.g. finely balanced

All data is subject to change without notice.



# MODEL EK2

## TECHNICAL SPECIFICATIONS



### Properties:

- easy assembly
- concentrically machined hubs
- vibration dampening
- electrically insulating
- backlash-free
- press-fit design

### Material:

Clamping hub: up to series 450 high strength aluminum, from series 800 and up steel  
Elastomer insert: precision molded, wear resistant, and thermally stable polymer

### Design:

Two coupling hubs are concentrically machined with concave driving jaws

### \*Speeds:

Over 10.000 rpm a finely balanced version is available

### Tolerance:

On the hub/shaft connection 0,01 to 0,05 mm

Model EK 2		Series																	
		20			60			150			300			450			800		
Type (Elastomer insert)		A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C
Rated torque (Nm)	$T_{KN}$	17	21	6	60	75	20	160	200	42	325	405	84	530	660	95	950	1100	240
Max. torque** (Nm)	$T_{Kmax}$	34	42	12	120	150	35	320	400	85	650	810	170	1060	1350	190	1900	2150	400
Overall length (mm)	A	66			78			90			114			126			162		
Outer diameter (mm)	B	42			56			66,5			82			102			136,5		
Outer diameter with screwhead (mm)	$B_s$	44,5			57			68			85			105			139		
Mounting length (mm)	C	25			30			35			45			50			65		
Inner diameter range H7 (mm)	$D_{1/2}$	8 - 25			12 - 32			19 - 35			20 - 45			28 - 60			35 - 80		
Inner diameter max. (elastomer) (mm)	$D_E$	19,2			27,2			30,2			38,2			46,2			60,5		
Mounting screw (ISO 4762/12.9)	E	M5			M6			M8			M10			M12			M16		
Tightening torque of the mounting screw (Nm)		8			15			35			70			120			290		
Distance between centers (mm)	F	15,5			21			24			29			38			50,5		
Distance (mm)	G	8,5			10			12			15			17,5			23		
Hub length (mm)	H	39			46			52,5			66			73			93,5		
Moment of inertia ( $10^{-3} \text{ kgm}^2$ )	$J_1/J_2$	0,02			0,09			0,2			0,6			1,5			9,5		
Approx. weight (kg)		0,15			0,35			0,6			1,1			1,7			10		
Speed* (rpm)		19.000			14.000			11.500			9.500			8.000			4.000		

Information about static and dynamic torsional stiffness as well as max. possible misalignment [see page 4](#)

1 Nm = 8,85 in lbs

\*\* Maximum transferable torque of the clamping hub depends on the bore diameters

Series	Ø 8	Ø 16	Ø 19	Ø 25	Ø 30	Ø 32	Ø 35	Ø 45	Ø 50	Ø 55	Ø 60	Ø 65	Ø 70	Ø 75	Ø 80
20	20	35	45	60											
60		50	80	100	110	120									
150			120	160	180	200	220								
300			200	230	300	350	380	420							
450					420	480	510	600	660	750	850				
800							700	750	800	835	865	900	925	950	1.000

Higher torque through additional key possible.

### Ordering example

EK2 / 60 / A / 19 / 24 / XX

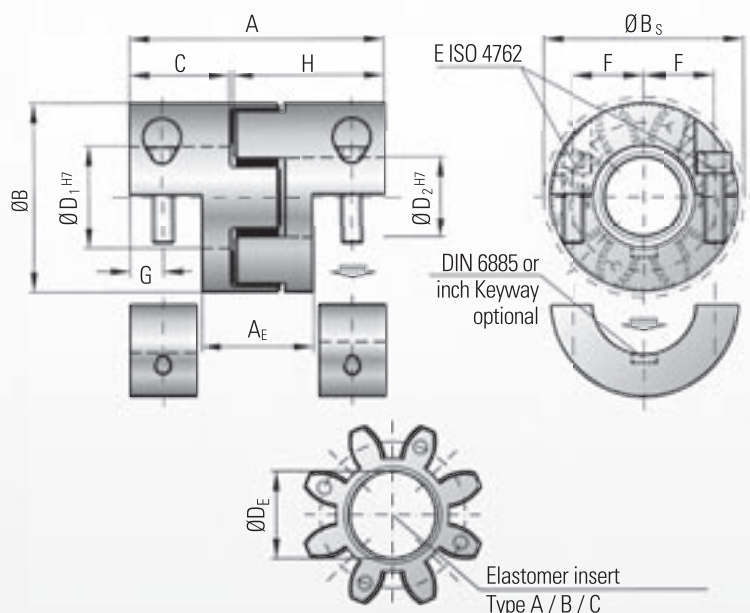
Model  
Series  
Type Elastomer insert  
Bore Ø D1 H7  
Bore Ø D2 H7  
Non standard e.g. finely balanced

All data is subject to change without notice.

optional  
stainless  
steel

# MODEL EKH

## TECHNICAL SPECIFICATIONS



### Properties:

- radial mounting possible
- high concentricity
- dampens vibrations
- electrical insulating
- easy mounting
- backlash-free

### Material:

Clamping hub: up to series 450 high strength aluminum, from series 800 and up steel  
Elastomer insert: precision molded, wear resistant, and thermally stable polymer

### Design:

Two split coupling hubs are concentrically machined with concave driving jaws

### \*Speeds:

Over 10.000 rpm a finely balanced version is available

### Tolerance:

On the hub/shaft connection 0,01 to 0,05 mm

Model EKH		Series																	
		20			60			150			300			450			800		
Type (Elastomer insert)		A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C
Rated torque (Nm)	$T_{KN}$	17	21	6	60	75	20	160	200	42	325	405	84	530	660	95	950	1100	240
Max. torque** (Nm)	$T_{Kmax}$	34	42	12	120	150	35	320	400	85	650	810	170	1060	1350	190	1900	2150	400
Overall length (mm)	A	66			78			90			114			126			162		
Insertion length (mm)	$A_E$	28			33			37			49			51			65		
Outer diameter (mm)	B	42			56			66,5			82			102			136,5		
Outer diameter with screwhead (mm)	$B_S$	44,5			57			68			85			105			139		
Mounting length (mm)	C	25			30			35			45			50			65		
Inner diameter range H7 (mm)	$D_{1/2}$	8 - 25			12 - 32			19 - 35			20 - 45			28 - 60			35 - 80		
Inner diameter max. (elastomer) (mm)	$D_E$	19,2			27,2			30,2			38,2			46,2			60,5		
Mounting screw (ISO 4762/12.9)		M5			M6			M8			M10			M12			M16		
Tightening torque of the mounting screw (Nm)	E	8			15			35			70			120			290		
Distance between centers (mm)	F	15,5			21			24			29			38			50,5		
Distance (mm)	G	8,5			10			12			15			17,5			23		
Hub length (mm)	H	39			46			52,5			66			73			93,5		
Moment of inertia (10 <sup>-3</sup> kgm <sup>2</sup> )	$J_1/J_2$	0,02			0,09			0,2			0,6			1,5			9,5		
Approx. weight (kg)		0,15			0,35			0,6			1,1			1,7			10		
Speed* (rpm)		19.000			14.000			11.500			9.500			8.000			4.000		

Information about static and dynamic torsional stiffness as well as max. possible misalignment see page 4

1 Nm = 8,85 in lbs

\*\* Maximum transferable torque of the clamping hub depends on the bore diameters

Serie	Ø 8	Ø 16	Ø 19	Ø 25	Ø 30	Ø 32	Ø 35	Ø 45	Ø 50	Ø 55	Ø 60	Ø 65	Ø 70	Ø 75	Ø 80
20	30	40	50	65											
60		65	120	150	180	200									
150			180	240	270	300	330								
300			300	340	450	520	570	630							
450					630	720	770	900	1.120	1.180	1.350				
800						1.050	1.125	1.200	1.300	1.400	1.450	1.500	1.550	1.600	

Higher torque through additional key possible.



## Split hubs

- radial mounting possible
- high concentricity
- dampens vibrations
- electrical insulating
- easy mounting
- backlash-free

Clamping hub: up to series 450 high strength aluminum, from series 800 and up steel  
Elastomer insert: precision molded, wear resistant, and thermally stable polymer

Two split coupling hubs are concentrically machined with concave driving jaws

Over 10.000 rpm a finely balanced version is available

On the hub/shaft connection 0,01 to 0,05 mm

## Ordering example

EKH / 60 / A / 19 / 24 / XX

Model

Series

Type Elastomer insert

Bore Ø D1 H7

Bore Ø D2 H7

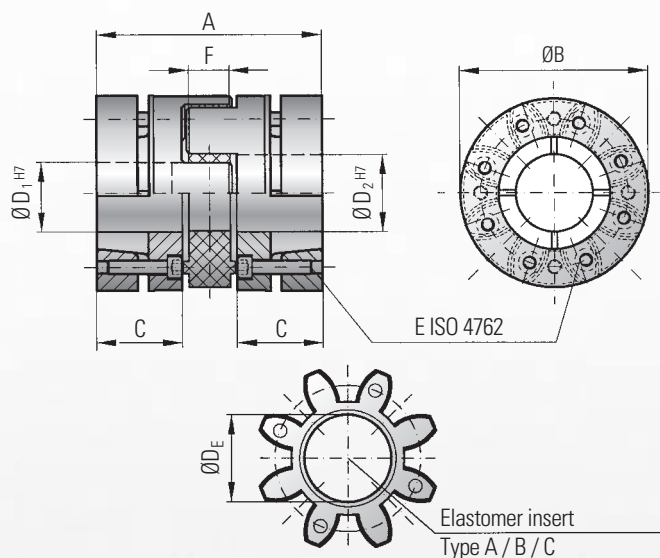
Non standard e.g. finely balanced

All data is subject to change without notice.



# MODEL EK6

## TECHNICAL SPECIFICATIONS



### Properties:

- high clamping forces
- concentrically machined
- easy mounting
- dampens vibrations
- electrical insulating
- backlash-free
- press-fit design
- axial mounting possible

### Material:

Clamping hub and conical clamping: up to series 450 high strength aluminum, from series 800 and up steel  
Elastomer insert: precision molded, wear resistant, and thermally stable polymer

### Design:

Two coupling hubs are concentrically machined with concave driving jaws

### Tolerance:

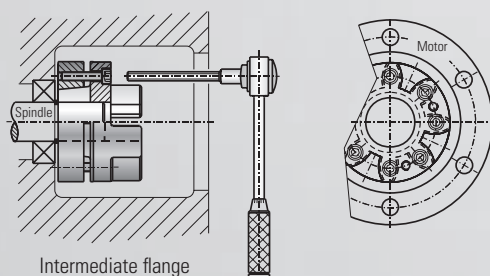
On the hub/shaft connection 0,01 to 0,05 mm

Model EK 6		Series																				
		10			20			60			150			300			450			800		
Type (Elastomer insert)		A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C
Rated torque (Nm)	$T_{KN}$	12,6	16	4	17	21	6	60	75	20	160	200	42	325	405	84	530	660	95	950	1100	240
Max. torque (Nm)	$T_{Kmax}$	25	32	6	34	42	12	120	150	35	320	400	85	650	810	170	1060	1350	190	1900	2150	400
Overall length (mm)	A	42			56			64			76			96			110			138		
Outer diameter (mm)	B	32			43			56			66			82			102			136,5		
Mounting length (mm)	C	15			20			23			28			36			42			53		
Inner diameter range H7 (mm)	$D_{1/2}$	6 - 16			8 - 24			12 - 32			19 - 35			20 - 45			28 - 54			32 - 80		
Inner diameter max. (elastomer) (mm)	$D_E$	14,2			19,2			27,2			30,2			38,2			46,2			60,5		
Mounting screw (ISO 4762/12.9)	E	3x M3			6x M4			4x M5			8x M5			8x M6			8x M8			8x M10		
Tightening torque of the mounting screw (Nm)		2			3			6			7			12			35			55		
Width Elastomer insert (mm)	F	9,5			12			14			15			18			20			25		
Moment of inertia ( $10^{-3} \text{ kgm}^2$ )	$J_1/J_2$	0,01			0,015			0,08			0,15			0,4			1,3			9,2		
Approx. weight (kg)		0,08			0,12			0,3			0,5			0,9			1,5			9,6		
Speed (1/min)		20.000			19.000			14.000			11.500			9.500			8.000			4.000		

Information about static and dynamic torsional stiffness as well as max. possible misalignment see page 4

1 Nm = 8,85 in lbs

Access holes in the mounting flange are not necessary for EK 6 couplings. The unique assembly screw design (shown below) allows for easy axial mounting and dismounting of the coupling.



### Ordering example

EK6 / 60 / A / 19 / 24 / XX

Model  
Series  
Type Elastomer insert  
Bore Ø D1 H7  
Bore Ø D2 H7  
Non standard e.g. anodized

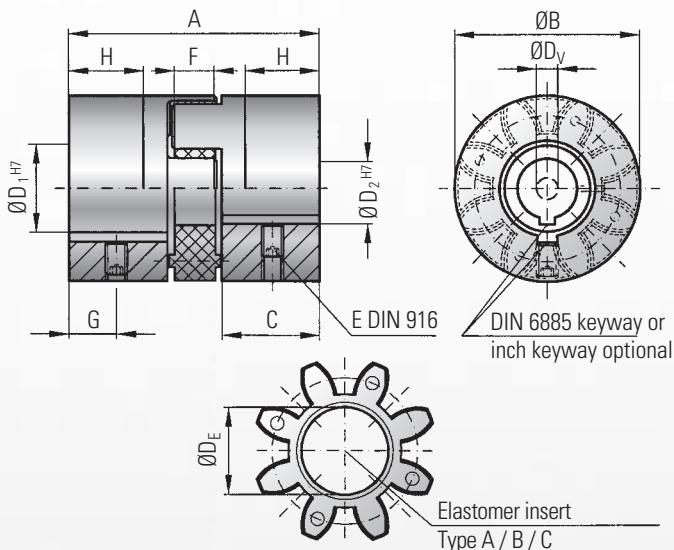
All data is subject to change without notice.



optional  
stainless steel

# MODEL EK1

## TECHNICAL SPECIFICATIONS



### Properties:

- economically priced
- concentrically machined
- dampens vibrations
- electrical insulating
- press-fit design
- low backlash, due to keyway connection

### Material:

Clamping hub: up to series 450 high strength aluminum, from series 800 and up steel  
Elastomer insert: precision molded, wear resistant, and thermally stable polymer

### Design:

Two coupling hubs are concentrically machined with concave driving claws  
Bore tolerance H7 + keyway + set screw  
DIN 916 or optional pilot bored (D<sub>v</sub>)

### \*Speeds:

Over 10.000 rpm a finely balanced version is available

### Tolerance:

On the hub/shaft connection 0,01 to 0,05 mm

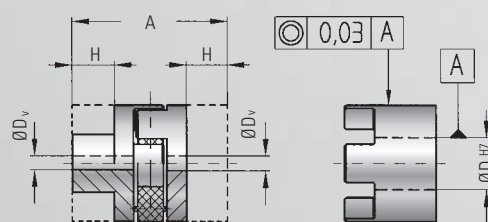
Model EK 1		Series																											
		2			5			10			20			60			150			300			450			800			
Type (Elastomer insert)		A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	
Rated torque (Nm)	T <sub>KN</sub>	2	2,4	0,5	9	12	2	12,5	16	4	17	21	6	60	75	20	160	200	42	325	405	84	450	660	95	950	1100	240	
Max. torque (Nm)	T <sub>Kmax</sub>	4	4,8	1	18	24	4	25	32	6	34	42	12	120	150	35	320	400	85	650	810	170	1060	1350	190	1900	2150	400	
Overall length (mm)	A	20			34			35			66			78			90			114			126			162			
Outer diameter (mm)	B	15			25			32			42			56			66,5			82			102			136,5			
Mounting length (mm)	C	6,5			12			12			25			30			35			45			50			65			
Inner diameter pilot bored (mm)	D <sub>V</sub>	2,8			4			6			7			9,5			14			18			22			29			
Inner diameter range H7 (mm)	D <sub>1/2</sub>	3 - 9			6 - 15			6 - 18			8 - 25			12 - 32			19 - 38			20 - 45			28 - 60			32 - 80			
Inner diameter max. (elastomer) (mm)	D <sub>E</sub>	6,2			10,2			14,2			19,2			27,2			30,2			38,2			46,2			60,5			
Set screws (DIN 916)	E	see table (depending on bore Ø)**																											
Width Elastomer insert (mm)	F	5			8			9,5			12			14			15			18			20			25			
Distance (mm)	G	3			5			6			9			11			12			15			17			30			
Possible shortening length (mm)	H	4			6			6			19			22			26			32			37			43			
Moment of inertia (10 <sup>-3</sup> kgm <sup>2</sup> )	J <sub>1</sub> /J <sub>2</sub>	0,0003			0,001			0,01			0,02			0,09			0,2			0,6			1,5			11,4			
Approx. weight (kg)		0,008			0,03			0,08			0,15			0,35			0,6			1,1			1,7			11			
Speed* (rpm)		28.000			22.000			20.000			19.000			14.000			11.500			9.500			8.000			4.000			

Information about static and dynamic torsional stiffness as well as max. possible misalignment see page 4

1 Nm = 8,85 in lbs

** Set screws	
D <sub>1</sub> /D <sub>2</sub>	E
Ø 6-10	M3
Ø 11-12	M4
Ø 13-30	M5
Ø 31-60	M8
Ø 59-80	M10

### Details of pilot bored coupling hubs (D<sub>v</sub>)



It's critical that modifications of the hub are machined concentrically and perpendicular to the through bore.

EK1 hubs can be modified to customer specifications.

The coupling hub may be shortened by measurement H.

### Ordering example

EK1 / 60 / A / 19 / D<sub>v</sub> / XX

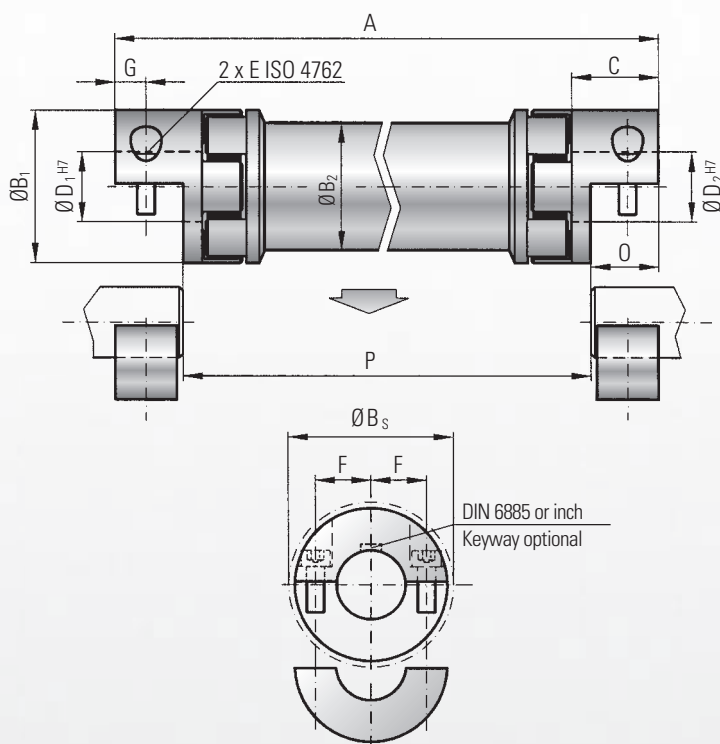
Model  
Series  
Type Elastomer insert  
Bore Ø D1 H7  
Bore Ø D2 prebored  
Non standard e.g. anodized

All data is subject to change without notice.



# MODEL EZ2

## TECHNICAL SPECIFICATIONS

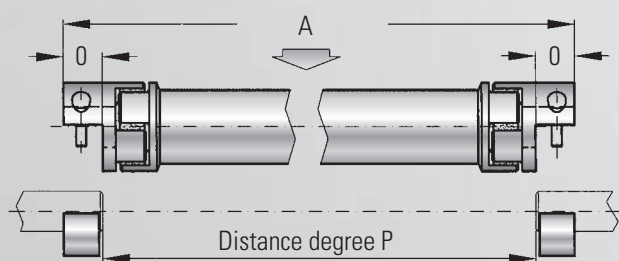


### Ordering example

	EZ2	/ 020	/ 1200	/ A	/ 24	/ 19	/ XX
Model							
Series							
Overall length							
Type Elastomer insert							
Bore Ø D1 H7							
Bore Ø D2 H7							
Non standard e.g. finely balanced							

All data is subject to change without notice.

### Assembly instructions



The total length of the axis is defined by the distance  $P + 2xØ$ .



### Properties:

- Due to split hubs radial mounting possible
- Spans distances of up to 4 m
- No intermediate support bearing required
- Low moment of inertia
- dampens vibrations
- press-fit design
- backlash-free

### Material:

Clamping hub: up to series 450 high strength aluminum, from series 800 and up steel  
Elastomer insert: precision molded, wear resistant, and thermally stable polymer  
Intermediate tube: precision machined aluminum tube; **steel and composite tube are optionally available**

### Design:

Two coupling hubs are concentrically machined with concave driving jaws  
Elastomer inserts are available in type A or B  
The two coupling elements are connected with a precise and concentrically machined aluminum tube

### Speed:

To control the critical resonant speed please advise the application speed when ordering or inquiring about EZ Line shafts

### Tolerance:

On the hub/shaft connection 0,01 to 0,05 mm

### Torsional stiffness:

To optimize the application different elastomer inserts with different shore hardnesses are available

### R+W calculation program

With a specially developed software R+W can calculate the critical resonant speeds for each application.

Results of a calculation are shown below.

The critical speed can be altered by changing the tube material and/or other parameters.

Critical resonant speed	$n_k$	=	1/min.
Torsional stiffness tube	$C_{TZW/R}$	=	Nm/rad
Total stiffness EZ 2	$C_{Tdyn}^{EZ}$	=	Nm/rad
Angle of twist	$\varphi$	=	Degree-Min-Sec
Weight of total axes	$m$	=	kg
Critical resonance speed	$n_e$	=	1/min
Mass moment of inertia	$J$	=	kgm <sup>2</sup>
Permissible lateral misalignment	$\Delta Kr$	=	mm



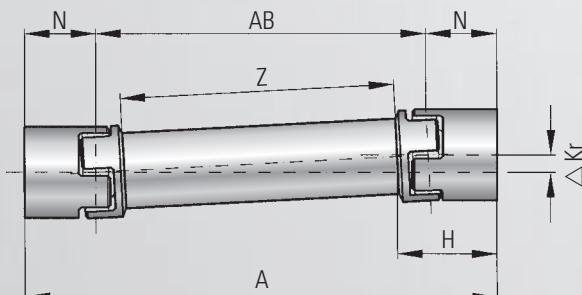
Model EZ 2		Series													
		10		20		60		150		300		450		800	
Type (Elastomer insert)		A	B	A	B	A	B	A	B	A	B	A	B	A	B
Rated torque (Nm)	$T_{KN}$	12,5	16	17	21	60	75	160	200	325	405	530	660	950	1100
Max. torque** (Nm)	$T_{Kmax}$	25	32	34	42	120	150	320	400	650	810	1060	1350	1900	2150
Overall length (mm)	A	95 - 4.000		130 - 4.000		175 - 4.000		200 - 4.000		245 - 4.000		280 - 4.000		320 - 4.000	
Outer diameter hub (mm)	$B_1$	32		42		56		66,5		82		102		136,5	
Outer diameter tube (mm)	$B_2$	28		35		50		60		76		90		120	
Outer diameter with screwhead (mm)	$B_S$	32		44,5		57		68		85		105		139	
Fit length (mm)	C	20		25		40		47		55		65		79	
Inner diameter range H7 (mm)	$D_{1/2}$	5 - 16		8 - 25		14 - 32		19 - 35		19 - 45		24 - 60		35 - 80	
Mounting screw (ISO 4762/12.9)		M4		M5		M6		M8		M10		M12		M16	
Tightening torque of the mounting screw (Nm)	E	4		8		15		35		70		120		290	
Distance between centers (mm)	F	10,5		15,5		21		24		29		38		50,5	
Distance (mm)	G	7,5		8,5		15		17,5		20		25		30	
Mounting length (mm)	O	16,6		18,6		32		37		42		52		62	
Moment of inertia ( $10^{-3} \text{ kgm}^2$ )	$J_1/J_2$	0,01		0,02		0,15		0,21		1,02		2,3		17	
Inertia of tube per meter ( $10^{-3} \text{ kgm}^2$ )	$J_3$	0,075		0,183		0,66		1,18		2,48		10,6		38	
Dynamic torsional stiffness of the couplings (Nm/rad)	$C_{Tdyn}^E$	270	825	1.270	2.220	3.970	5.950	6.700	14.650	11.850	20.200	27.700	40.600	41.300	90.000
Torsional stiffness of tube per meter (Nm <sup>2</sup> /rad)	$C_T^{ZWR}$	321		1.530		6.632		11.810		20.230		65.340		392.800	
Distance between centers (mm)	N	26		33		49		57		67		78		94	
Length of the couplings (mm)	H	34		46		63		73		86		99		125	

Information about static and dynamic torsional stiffness as well as max. possible misalignment see page 4

1 Nm = 8,85 in lbs  
\*\* Max. transferable torque of the clamping hub see EKH (page 7)

## The selection process for Servo-Insert-Couplings EZ 2

A	Overall length	m	$C_{Tdyn}^E$	Dynamic torsional stiffness of both elastomer inserts	Nm/rad	H	Length of the coupling	mm
AB	Length AB = (A - 2xN)	m	$C_T^{ZWR}$	Torsional stiffness of tube per meter	Nm <sup>2</sup> /rad	N	Distance between center lines	mm
Z	Tube length	m	$C_{Tdyn}^{EZ}$	Torsional stiffness of entire coupling	Nm/rad	$M_{max}$	Max. torque	Nm
	Z = (A - 2xH)					$\varphi$	Angle of twist	degree



### ■ According to torsional stiffness

$$C_{Tdyn}^{EZ} = \frac{C_{Tdyn}^E \times (C_T^{ZWR}/Z)}{C_{Tdyn}^E + (C_T^{ZWR}/Z)} \text{ (Nm/rad)}$$

### ■ According to angle of twist

$$\varphi = \frac{180}{\pi} \times \frac{M_{max}}{C_{Tdyn}^{EZ}} \text{ (degree)}$$

### ■ Max. possible misalignments



$$\Delta Kr_{max} = \tan \Delta \frac{Kw}{2} \cdot AB$$

$$AB = A - 2xN$$



$$\Delta Kw_{max} = \text{ca. } 2^\circ$$

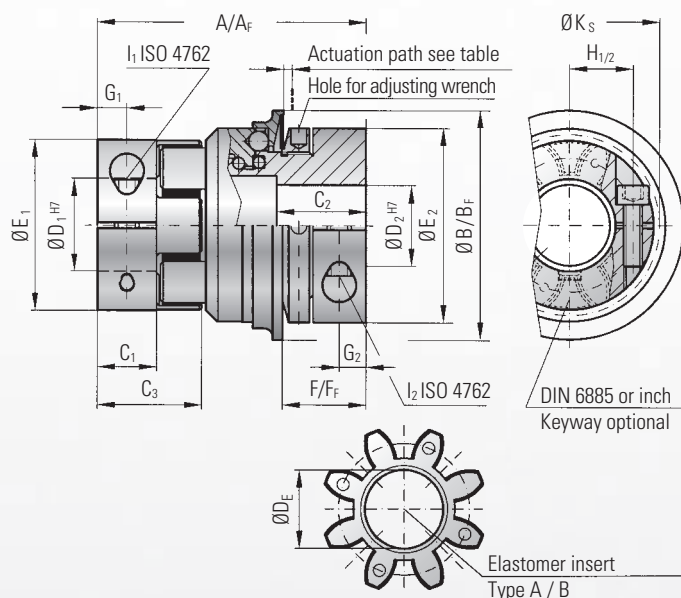


$$\Delta Ka_{max} = \text{ca. } \pm 2$$



# MODEL ES2

## TECHNICAL SPECIFICATIONS



### W = single position re-engagement

- After the overload has been eliminated, the coupling will automatically reengage precisely 360° from the original disengagement position
- Achievement of the precise synchronus re-engagement due to patented R+W design
- Signal at overload with mechanical switch or proximity sensor

### D = Multi position re-engagement

- Coupling re-engages at multiple set angular intervals.
- Immediate availability of the application as soon as the overload has been eliminated.
- Signal at overload with mechanical switch or proximity sensor
- Standard engagement every 60°
- Engagement at 30, 45, 90 and 120 degrees are optional.

### F = Full disengagement

- Permanent separation of drive and driven loads in the event of a torque overload.
- No residual friction
- Signal at overload
- Rotating elements slow down freely
- Coupling can be re-engaged manually (Engagement every 60°)

### Properties:

- reliable torque overload protection
- short compact design
- backlash-free due to patented R+W design
- disengagement within msec.
- high actuation path when disengaging
- electrically insulating
- press-fit design

### Material:

Torque limiter: high strength hardened steel with rust protected surface (oxidized)  
Clamping hub D<sub>1</sub>: up to series 450 high strength aluminum, from series 800 and up steel  
Clamping hub D<sub>2</sub>: up to series 60 high strength aluminum, from series 150 and up steel  
Elastomer insert: precision molded, wear resistant, and thermally stable polymer

### Design:

Two coupling hubs are concentrically machined with concave driving jaws  
One side with an integrated torque limiter  
The torque limiter is available in single position, multi position or full-disengagement versions.

### Tolerance:

On the hub/shaft connection 0,01 to 0,05 mm

**For table see right page.**

### Ordering example

ES2 / 10 / A / W / 14 / 12 / 8 / 4-12 / XX

Model  
Series  
Type Elastomer insert  
Function system (see page 13)  
Bore  $\Delta D_1 H7$   
Bore  $\Delta D_2 H7$   
Disengagement torque  
Adjustable range  
Non standard e.g. VA-Material

All data is subject to change without notice.

### The selection of torque limiters

In general the torque limiters are sized according to the necessary disengagement torque. This torque must exceed the nominal torque of the application.

For more information see page 18.



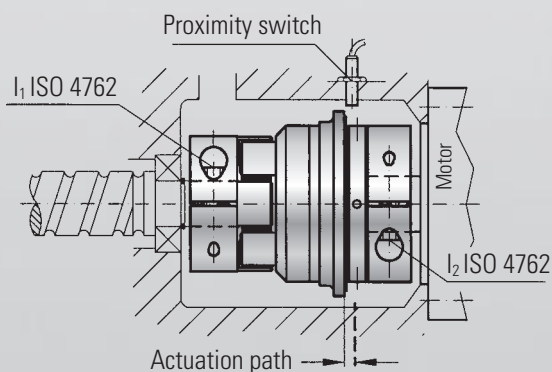


Model ES 2		Series													
		10		20		60		150		300		450		800	
Adjustment range (Nm) possible from -to (approx. values)	T <sub>KN</sub>	2 - 6 or 4 - 12		10 - 25 or 20 - 40		10 - 30 or 25 - 80		20 - 70 or 40 - 170		100 - 200 150 - 240 200 - 320		80 - 200 200 - 350 300 - 500		400 - 650 500 - 800 600 - 900	
Adjustment range (full disengagement) (Nm) possible from -to (approx. values)	T <sub>KN</sub> <sup>F</sup>	4 - 10		8 - 20 or 16 - 30		20 - 40 or 30 - 60		80 - 150		120 - 180 or 180 - 300		60 - 150 100 - 300 250 - 500		200 - 400 or 450 - 800	
Overall length (mm)	A	60		86		96		106		140		164		179	
Overall length (full disengagement) (mm)	A <sub>F</sub>	60		86		96		108		143		168		190	
Outer diameter of actuation ring (mm)	B	45		65		73		92		120		135		152	
Outer diameter of actuation ring (mm)	B <sub>F</sub>	51,5		70		83		98		132		155		177	
Fit length (mm)	C <sub>1</sub>	10,3		17		20		21		31		34		46	
Fit length (mm)	C <sub>2</sub>	16		27		31		35		42		51		45	
Length of hub (mm)	C <sub>3</sub>	20,7		31		36		39		52		57		74	
Inner diameter from Ø to Ø H7 (mm)	D <sub>1</sub>	5 - 16		8 - 25		12 - 32		19 - 35		20 - 45		28 - 60		35 - 80	
Inner diameter from Ø to Ø H7 (mm)	D <sub>2</sub>	6 - 20		12 - 30		15 - 32		19 - 42		30 - 60		35 - 60		40 - 75	
Diameter of the hub (mm)	E <sub>1</sub>	32		42		56		66,5		82		102		136,5	
Diameter of the hub (mm)	E <sub>2</sub>	40		55		66		81		110		123		132	
Distance (mm)	F	17		24		30		31		35		45		50	
Distance full disengagement (mm)	F <sub>F</sub>	16		22		29		30		35		43		54	
Distance (mm)	G <sub>1</sub>	5		8,5		10		11		15		17,5		23	
Distance (mm)	G <sub>2</sub>	5		7,5		9,5		11		13		17		18	
Distance between centers (mm)	H <sub>1</sub>	10,5		15		21		24		29		38		50,5	
Screws (ISO 4762/12.9)	I <sub>1</sub>	M4		M5		M6		M8		M10		M12		M16	
Tightening torque of the mounting screw (Nm)		4		8		15		35		70		120		290	
Distance between centers SK-side (mm)	H <sub>2</sub>	15		19		23		27		39		41		48	
Screws (ISO 4762/12.9)	I <sub>2</sub>	M4		M6		M8		M10		M12		M16		2x M16	
Tightening torque of the mounting screw (Nm)		4,5		15		40		70		130		200		250	
Diameter with screwhead (mm)	K <sub>S</sub>	32		44,5		57		68		85		105		139	
Approx. weight (kg)	J <sub>ges</sub>	0,3		0,6		1,0		2,4		5,8		9,3		14,3	
Moment of inertia (10 <sup>-3</sup> kgm²)		0,06		0,25		0,7		2,3		11		22		33,5	
Actuation path (mm)		1,2		1,5		1,7		1,9		2,2		2,2		2,2	
Type (Elastomer insert)		A	B	A	B	A	B	A	B	A	B	A	B	A	B
Inner diameter (Elastomer insert) (mm)	D <sub>F</sub>	14,2		19,2		27,2		30,2		38,2		46,2		60,5	

Information about static and dynamic torsional stiffness as well as max. possible misalignment see page 4

1 Nm = 8,85 in lbs

## Mounting instructions



**Mounting:** Slide the coupling on the shaft ends to the proper axial position. Using a torque wrench, tighten the clamp screws to the correct tightening torque as indicated (in the table page 12)

**CAUTION!** Both clamping hubs have different screws and different tightening torques.

**Dismounting:** Simply loosen the clamp screw I1, I2 and remove the safety coupling.

**Emergency cut off:** The axial path of the actuation ring activates the mechanical switch or the proximity sensor.

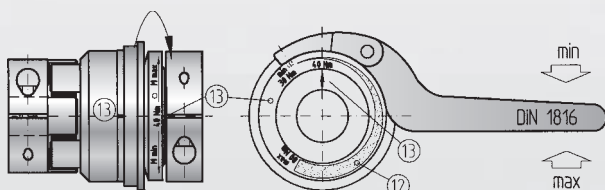
**CAUTION!** Upon assembly, it is absolutely necessary to check the function of the switch 100%

# FUNCTION SYSTEMS ES2

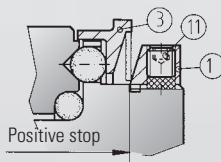
**R+W torque limiting couplings are ball detent style overload couplings. They protect drive and driven mechanical components from damage associated with torque overloads.**

- Backlash free torque transmission is accomplished by a series of steel balls (4) nested in hardened detents (5).
- Disc springs push against an actuation ring (3) keeping the balls nested.
- The disengagement torque is adjustable by means of an adjustment nut (1).
- In the event of an overload, the actuation ring (3) moves axially allowing the balls to come off the detents separating the drive and driven elements.
- The movement of the actuation ring (3) can be sensed by means of a mechanical switch or proximity sensor (6) triggering the drive to shut down.

## Disengagement torque setting



At ES 2 couplings, the slot of the clamping hub serves as a marking (13).



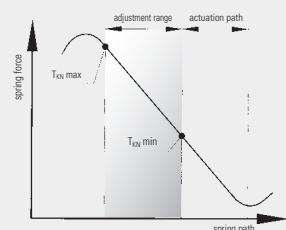
- |                        |                     |
|------------------------|---------------------|
| 1 adjustment nut       | 12 adjustment range |
| 11 locking screw       | 13 marking          |
| 3 steel actuation ring |                     |

R+W torque limiters are factory set to the customer specified disengagement torque, which is marked onto the coupling. The adjustment range (min/max) is also marked on the adjustment nut (1).

The customer can adjust the disengagement torque as long as it is in the range (12) indicated on the adjustment nut.

The adjustment range may not be exceeded while re-adjusting.

To adjust the disengagement torque, loosen the locking screws (11) and rotate the adjustment ring using a spanner wrench to the desired new setting. Tighten the 3 locking screws (11) and test the coupling.

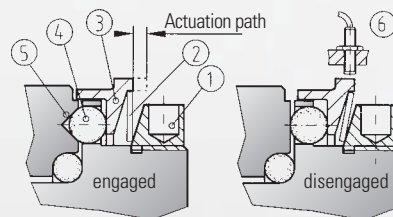


### CAUTION:

R+W torque limiters incorporate disc springs that exhibit a special spring characteristic. It is important to stay in the max-min range of the coupling.

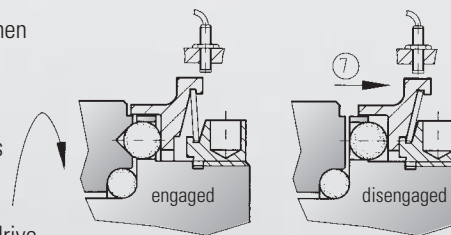
## Single-position / Multi-position

In a torque overload, with the single-position design (standard) and multi-position design, the spring disengages to allow the balls to come out of their detents, separating the drive and driven elements. Very low residual spring pressure remains so that the coupling will re-engage once the torque is reduced below the overload setting.



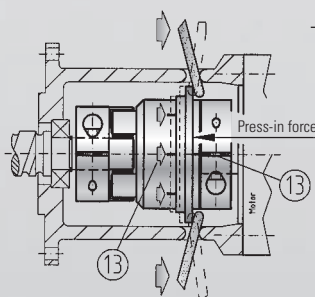
## Full-disengage

With this design, when a torque overload is detected, the disc spring completely flips over and places no residual spring pressure on the actuation ring. The drive and driven elements are completely separated.

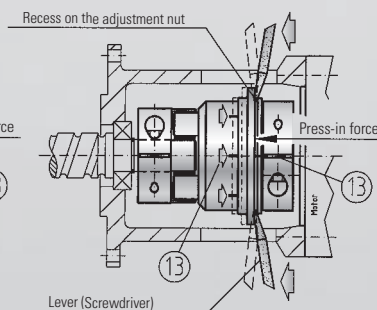


**Re-engagement of the coupling is not automatic and must be performed manually (Picture 3a, 3b).**

**CAUTION:**  
Re-engagement should only be performed when the coupling stands still and not rotating!



Picture 3a



Picture 3b

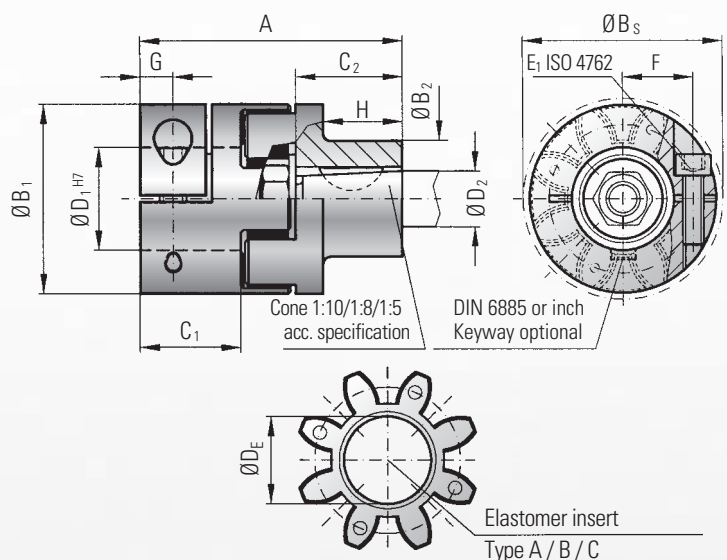
The R+W full-disengage torque limiting coupling can be re-engaged in six different positions or every 60 degrees with low „press-in“ force (E). Marks on the actuation ring and body (13) of the coupling must line up and indicate the re-engagement points.

As of size 200 and up the re-engagement can be done with 2 lever which will be supported at a recess on the adjustment nut (picture 3b). Screwdrivers can be used as a lever.

optional  
stainless  
steel

# MODEL EK4

## TECHNICAL SPECIFICATIONS



### Properties:

- for conical shaft ends
- short compact design
- easy assembly
- high concentricity
- backlash-free
- electrically insulating

### Material:

Clamping hubs: high strength aluminum  
Conical hub: steel  
Elastomer insert: precision molded, wear resistant, and thermally stable polymer

### Design:

Two coupling hubs are concentrically machined with concave driving jaws  
One side with clamping hub and a radial screw ISO 4762  
One side with a hub conically bored with keyway according to customer requirement

### Speed:

Over 10.000 rpm a finely balanced version is available

### Tolerance:

On the hub/shaft connection 0,01 to 0,05 mm

Model EK 4			Series								
			20			60			150		
Type (Elastomer insert)			A	B	C	A	B	C	A	B	C
Rated torque	(Nm)	T <sub>KN</sub>	17	21	6	60	75	20	160	200	42
Max. torque*	(Nm)	T <sub>Kmax</sub>	34	42	12	120	150	35	320	400	85
Overall length	(mm)	A	57			77			84		
Outer diameter hub	(mm)	B <sub>1</sub>	42			56			66,5		
Outer diameter conical hub	(mm)	B <sub>2</sub>	20			28			30		
Outer diameter with screwhead	(mm)	B <sub>S</sub>	44,5			57			68		
Mounting length	(mm)	C <sub>1</sub>	25			30			35		
Mounting length	(mm)	C <sub>2</sub>	16			29			29		
Inner diameter range H7	(mm)	D <sub>1</sub>	8-25			12-32			19-35		
Possible conical diameter	(mm)	D <sub>2</sub>	Acc. to customer requirement								
Inner diameter max (elastomer)	(mm)	D <sub>E</sub>	19,2			27,2			30,2		
Mounting screw (ISO 4762/12.9)		E <sub>1</sub>	M5			M6			M8		
Tightening torque of the mounting screw	(Nm)		8			15			35		
Distance between centers	(mm)	F	15,5			21			24		
Distance	(mm)	G	8,5			10			12		
Length	(mm)	H	9,5			21			19		

Information about static and dynamic torsional stiffness as well as max. possible misalignment see page 4

1 Nm = 8,85 in lbs

\*\* Maximum transferable torque of the clamping hub depends on the bore diameters (bore/shaft clearance 0,01 mm to 0,05 mm shaft oiled)

Series	Ø 8	Ø 16	Ø 19	Ø 25	Ø 30	Ø 32	Ø 35
20	20	35	45	60			
60		50	80	100	110	120	
150			120	160	180	200	220

Higher torque through additional key possible.



### Ordering example

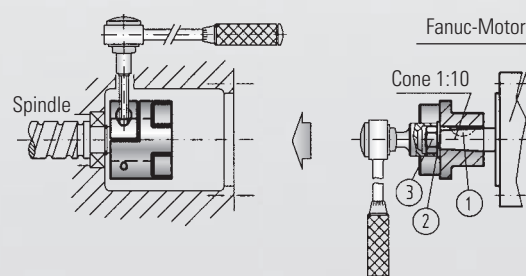
EK4 / 20 / A / 24 / 1:10 Ø11 / XX

Model  
Series  
Type Elastomer insert  
Bore Ø D1 H7  
Cone/ Ø D2  
Non standard e.g. finely balanced

All data is subject to change without notice.

### Installation instruction

**Mounting of the clamping hub:** Slide the coupling on the shaft ends, at the right axial position tighten the mounting screw to the specified tightening torque as shown in the table ( column E1).

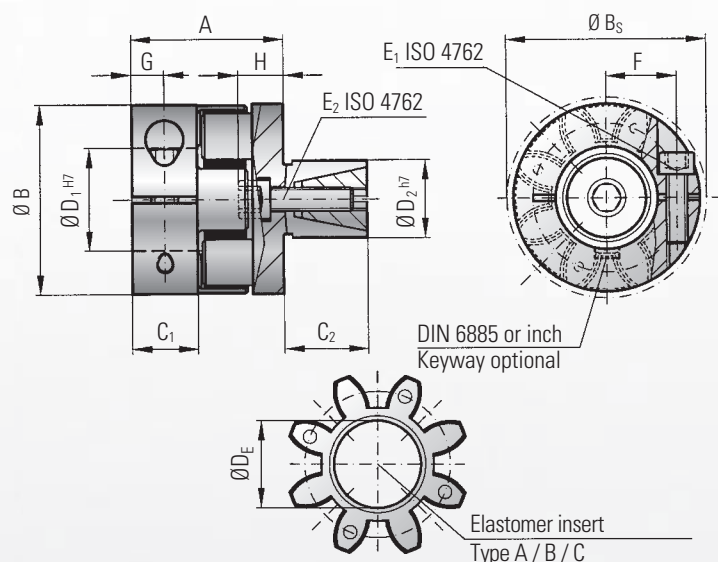


**Mounting of the conical hub:** After inserting the key into the keyway of the motor shaft slide the coupling hub on the shaft. Check if the conical hub has a proper seat on the shaft. Now the nut (3) can be tightened on the motor shaft using the exact tightening torque specified by the motor manufacturer.



# MODEL EK7

## TECHNICAL SPECIFICATIONS



### Properties:

- short compact design
- easy mounting
- high concentricity
- axial mounting of the expanding shaft
- backlash-free
- electrical insulating

### Material:

Clamping hub: up to series 450 high strength aluminum, from series 800 and up steel  
Expanding shaft & cone: steel  
Elastomer insert: precision molded, wear resistant, and thermally stable polymer

### Design:

Two coupling hubs are concentrically machined with concave driving jaws  
One side with clamping hub and a radial screw ISO 4762  
One side with an expanding shaft and tapered clamping element  
Suggested bore tolerance for the shaft: H7

### Speed\*\*:

Over 4.000 rpm a finely balanced version is available

### Tolerance:

On the hub/shaft connection 0,01 to 0,05 mm

Model EK7			Series																							
			5			10			20			60			150			300			450			800		
Type (Elastomer insert)			A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C	A	B	C
Rated torque (Nm)	$T_{KN}$		9	12	2	12,5	16	4	17	21	6	60	75	20	160	200	42	325	405	84	530	660	95	950	1100	240
Max. torque* (Nm)	$T_{Kmax}$		18	24	4	25	32	6	34	42	12	120	150	35	320	400	85	650	810	170	1060	1350	190	1900	2150	400
Overall length (mm)	A		22			28			40			46			51			68			76			94		
Outer diameter (mm)	B		25			32			42			56			66,5			82			102			135		
Outer diameter with screwhead (mm)	$B_S$		25			32			44,5			57			68			85			105			139		
Mounting length (mm)	$C_1$		8			10,3			17			20			21			31			34			46		
Mounting length (mm)	$C_2$		12			20			25			27			32			45			55			60		
Inner diameter range H7 (mm)	$D_1$		4 - 12,7			5 - 16			8 - 25			12 - 32			19 - 35			20 - 45			28 - 60			35 - 80		
Outer diameter range H7 (mm)	$D_2$		10 - 16			13 - 25			14 - 30			23 - 36			26 - 42			38 - 60			42 - 70			42 - 80		
Inner diameter max. (elastomer) (mm)	$D_E$		10,2			14,2			19,2			27,2			30,2			38,2			46,2			60,5		
Mounting screw (ISO 4762/12.9)	$E_1$		M3			M4			M5			M6			M8			M10			M12			M16		
Tightening torque (Nm)			2			4			8			15			35			70			120			290		
Mounting screw (ISO 4762/12.9)	$E_2$		M4			M5			M6			M8			M10			M12			M16			M16		
Tightening torque (Nm)			4			9			12			32			60			110			240			300		
Distance between centers (mm)	F		8			10,5			15,5			21			24			29			38			50,5		
Distance (mm)	G		4			5			8,5			10			11			15			17,5			23		
Length (mm)	H		7			7			10			11			16			20			27			27		
Moment of inertia ( $10^{-3} \text{ kgm}^2$ )			0,002			0,01			0,04			0,08			0,15			0,4			1,3			9,5		
Approx. weight (kg)			0,04			0,05			0,12			0,3			0,5			0,9			1,5			7,6		
Speed** (rpm)			22.000			20.000			19.000			14.000			11.500			9.500			8.000			4.000		

Information about static and dynamic torsional stiffness as well as max. possible misalignment see page 4

1 Nm = 8,85 in lbs

\* Maximum transferable torque of the clamping hub depends on the bore diameters (bore/shaft clearance 0,01 mm to 0,05 mm shaft oiled)



# TECHNICAL INFORMATION EK7

Series	Ø 3	Ø 4	Ø 5	Ø 8	Ø 16	Ø 19	Ø 25	Ø 30	Ø 32	Ø 35	Ø 45	Ø 50	Ø 55	Ø 60	Ø 65	Ø 70	Ø 75	Ø 80
5		1,5	2	8														
10			4	12	32													
20				20	35	45	60											
60					50	80	100	110	120									
150						120	160	180	200	220								
300						200	230	300	350	380	420							
450								420	480	510	600	660	750	850				
800										700	750	800	835	865	900	925	950	1.000

Higher torque through additional keyway possible.

## Ordering example

EK7 / 20 / A / 24 / 19 / XX

Model

Series

Type Elastomer insert

Bore Ø D1 H7

Shaft Ø D2 H7

Non standard e.g. finely balanced

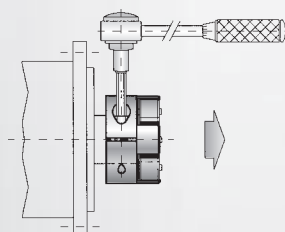
All data is subject to change without notice.

## Mounting instructions

### Mounting of the clamping hub:

Slide the coupling onto the shaft ends, at the right axial position tighten the mounting screw to the specified tightening torque  $E_1$ .

See page 16/column  $E_1$ .



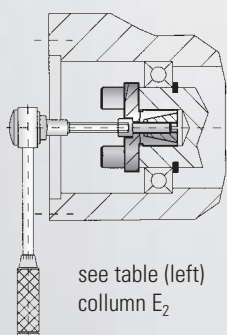
### Dismounting of the clamping hub:

For dismounting loosen the mounting screw  $E_1$ .

### Mounting of the expanding shaft:

Push the shaft hub into the bore, at the right axial position tighten the mounting screw to the specified tightening torque  $E_2$ .

See page 16/column  $E_2$ .



### Dismounting of the expanding shaft:

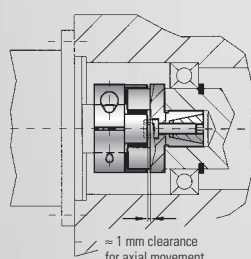
For dismounting loosen the screw  $E_2$  a few turns.

By putting pressure on the screwhead, the inner cone slides out of its sleeve.

The shaft is now loose.

### Advantage:

No access holes in the intermediate flange are necessary in order to mount the coupling.



≈ 1 mm clearance for axial movement

### CAUTION:

The elastomer insert has to be able to axially move in order to compensate for axial misalignment.



# FACTORS AND SIZING CALCULATIONS

## Temperature factor $S_v$

	A	B	C
Temperature (v)	Sh 98 A	Sh 64 D	Sh 80 A
> -30° to -10°	1,5	1,7	1,4
> -10° to +30°	1,0	1,0	1,0
> +30° to +40°	1,2	1,1	1,3
> +40° to +60°	1,4	1,3	1,5
> +60° to +80°	1,7	1,5	1,8
> +80° to +100°	2,0	1,8	2,1
> +100° to +120°	—	2,4	—

## Start factor $S_z$

$Z_h$	up to 120	120 - 240	above 240
$S_z$	1,0	1,3	on request

## Shock and load factor $S_A$

Uniform load	$S_A = 1,0$
Non-uniform load	$S_A = 1,8$
High dynamics, frequent reversing loads	$S_A = 2,5$

- $T_{KN}$  = Rated torque of the coupling (Nm)
- $T_{Kmax}$  = Max. torque of the coupling (Nm)
- $T_S$  = Existing peak torque of the coupling (Nm)
- $T_{AS}$  = Peak torque of the drive element (Nm)
- $T_{AN}$  = Rated torque of the drive element (Nm)
- $T_{LN}$  = Rated torque of the driven element (Nm)
- $P_{LN}$  = Power of the driven element (KW)
- $n$  = Speed (rpm)
- $J_A$  = Motor's moment of inertia (kgm<sup>2</sup>)
- $J_L$  = Machine's moment of inertia (kgm<sup>2</sup>) (Spindle + slide + workpiece)
- $J_1$  = Moment of inertia of a coupling half at the driving end (kgm<sup>2</sup>)
- $J_2$  = Moment of inertia of a coupling half at the driven end (kgm<sup>2</sup>)
- $m$  = Ratio of the moments of inertia driving to driven element
- $v$  = Temperature of the area around the coupling (observe radiant heat)
- $S_v$  = Temperature factor
- $S_A$  = Shock or load factor
- $S_z$  = Start factor (factor for the number of starts/hour)
- $Z_h$  = Cycle of starts (1/h)

## Sizing of a Servomax® Elastomer Coupling

### 1. Calculation example without shock or reversing loads

The rated torque of the coupling ( $T_{KN}$ ) needs to be higher than the rated torque of the driven element ( $T_{LN}$ ) times the temperature factor  $S_v$  at the coupling for the application. If  $T_{LN}$  is not known,  $T_{AN}$  can be used for the calculation instead.

Condition:

$$T_{KN} > T_{LN} \times S_v$$

Auxiliary calculation:

$$T_{LN} = \frac{9550 \times P_{LN}}{n}$$

#### Calculation example: (No loads and shocks)

Drive face: DC - motor

$$T_{AN} = 119 \text{ Nm}$$

Coupling conditions:

$$v = 70^\circ \text{C}$$

$$S_v = 1,7 \text{ (for } 70^\circ \text{C/Type A)}$$

Driven face: Pump

$$T_{LN} = 85 \text{ Nm}$$

Condition:

$$T_{KN} > T_{LN} \times S_v$$

$$T_{KN} > 85 \text{ Nm} \times 1,7$$

$$T_{KN} \geq 144,5 \text{ Nm}$$

Result:

A coupling type **EK 2/150/A** ( $T_{KN} = 160 \text{ Nm}$ ) is selected.

### 2. Calculation example with shock loads

In all cases the maximum rated torque ( $T_{Kmax}$ ) of the coupling can not be exceeded. First calculate the rated torque ( $T_{KN}$ ) of the coupling same as above. Compare this result to the peak torque ( $T_S$ ) times the start factor ( $S_z$ ) times the temperature factor ( $S_v$ ) for the application. The greater of the two values must be less than ( $T_{Kmax}$ ) of the coupling.

Condition:

$$T_{KN} > T_{LN} \times S_v$$

Auxiliary calculation:

$$T_{LN} = \frac{9550 \times P_{LN}}{n}$$

Condition:

$$T_{Kmax} > T_S \times S_z \times S_v$$

Auxiliary calculation:

$$T_S = \frac{T_{AS} \times S_A}{m + 1}$$

$$m = \frac{J_A + J_1}{J_L + J_2}$$

optional  
stainless  
steel

# MODEL ATEX

FOR USE IN HAZARDOUS AREAS AND EXPLOSIVE ATMOSPHERE

The ATEX 95 / ATEX 137 is regulated by the new European directive. Generally the explosive atmosphere is classified in 3 different zones.

## Zone 0:

A place in which an explosive atmosphere is consisting out of a mixture of air and flammable substances in the form of gas, vapor or mist is present frequently, continuously or for longer periods

## Zone 20:

Is relevant for an explosive atmosphere in the form of clouds of combustible dust in air under the same conditions as above.

## Zone 1:

Described as a place in which an explosive atmosphere is existing of a mixture of air and flammable substances in the form of gas, vapor or mist is likely to occur in normal operation occasionally.

## Zone 21:

Is relevant for an explosive atmosphere in the form of clouds of combustible dust in air under the same conditions as above.

## Zone 2:

A Place in which an explosive atmosphere is consisting out of mixture with air of flammable substances in the form of gas, vapor or mist is not likely to occur in normal operation but, if it does occur, it will persist for a short period only.

## Zone 22:

Relevant for an explosive atmosphere in the form of a cloud of combustible dust in air under the same conditions as above.

## Design of the Servomax EX:

### Hubs:

### Elastomer insert:

### Mounting, Sizing:

### Maintenance:

### Mounting manuals:

AT mosphere EX plosible

No dimensional change of the EK standard series. The material of the hubs and the inserts will change.

In general steel or stainless steel hubs will be used  
**Caution:** Aluminum hubs may not be used in explosive environment.

A special elastomer insert (Type D/92 Sh A), which is able to conduct electricity is used. This prevents the possibility of electrostatic loads and sparks.

All misalignment values and the transmittable torques are reduced by 30%.

A routine inspection of the coupling must be performed.

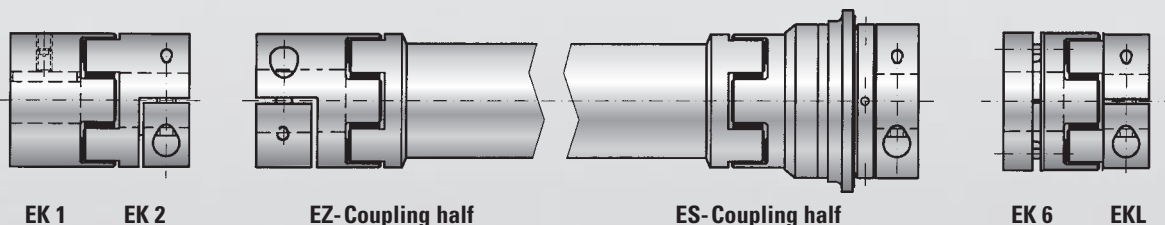
Mounting and maintenance manuals are provided with every EX coupling.

For the classified zones 1/21 and 2/22 the Servomax® Elastomer Coupling do have an accreditation according to ATEX 95/137

## R+W solutions with standard components

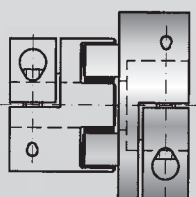
All standards hubs and elastomer inserts are interchangeable in the same sizes.

Example:



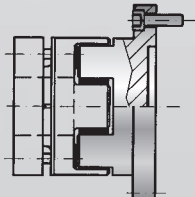
## R+W non standard solutions with special hubs

### EK 2 Non standard hub



Non standard hubs for bigger bores

### EK 6 Non standard hub

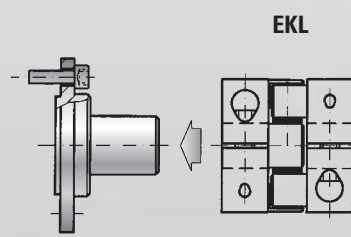


Non-standard hubs with flange

### EK 2 Non standard hub



Intermediate piece for higher lateral misalignment



Adapter flange for planetary gearboxes acc. to ISO 9409

**Experience and  
Know-how  
for your special  
requirements.**

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Registration No. 9605022

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## THE R+W-PRODUCT RANGE



### **TORQUE LIMITERS Series SK**

From 0,1 – 2.800 Nm, Bore diameters 4 – 100 mm  
Available as a single position, multi-position, load holding, or full disengagement version  
Single piece or press-fit design



### **BELLOWS COUPLINGS Series BK**

From 15 – 10.000 Nm  
Bore diameters 10 – 180 mm  
Single piece or press-fit design



### **BELLOWS COUPLINGS ECONOMY CLASS Series BKL**

From 2 – 500 Nm  
Bore diameters 4 – 62 mm



### **LINE SHAFTS Series ZA/ZAe**

From 10 – 4.000 Nm  
Bore diameters 10 – 100 mm  
Available up to 6 mtr. length



### **MINIATURE BELLOWS COUPLINGS Series MK**

From 0,05 – 10 Nm  
Bore diameters 1 – 28 mm  
Single piece or press-fit design



### **SERVOMAX® ELASTOMER COUPLINGS Series EK**

From 5 – 2.000 Nm, Shaft diameters 5 – 80 mm  
backlash-free, press-fit design



### **LINEAR COUPLINGS Series LK**

From 70 – 2.000 N  
Thread M5 – M16



### **POLYAMID COUPLINGS MICROFLEX Series FK 1**

Rated torque 1 Ncm  
Bore diameters 1 – 1,5 mm